

Z1 motor B2



Caratteristiche Tecniche

- Backlash= 6 arcmin
- Communication Method= RS 485
- Maximum Torque= 33N·m
- Encoder Resolution= 15bit
- Weight= 405g
- Force Control Accuracy= 0.2N·m
- Size= $\Phi 65 \times 52$ mm
- Control Frequency= 1KHz
- Reducer= Harmonic Reducer
- Bearing= Industrial grade cross roller
- Reduction Ratio= 60+
- Motor Sensing Feedback= Torque, Angle, Angular Velocity
- Voltage= 24V(Recommend)
- Motor Control Command= Torque, Angle, Angular Velocity, Stiffness, Damping